

Amendments to the Abstract:

Please amend the Abstract of the Disclosure as submitted herewith on a separate unnumbered page.

~~The invention relates to a~~ A device (15) for detecting a momentary distance (A) between a motor vehicle (7) and an obstacle is provided. The device includes (8, 8'), comprising distance sensors (1-6) and a control unit that (10). It is essential to the invention here that the control unit (10) is designed to calculate a driving path (11), to be traveled through in future by the motor vehicle. The driving path is calculated (7), using dynamic vehicle data and in that the control unit (10) is designed to differentiate between relevant obstacles (8') which are located within the driving path (11), and irrelevant obstacles (8) which are located outside the driving path (11). A method for detecting a momentary distance between a motor vehicle and an obstacle is also provided.

~~The invention also relates to a method for detecting a momentary distance (A) between a motor vehicle (7) and an obstacle (8, 8').~~

(Fig. 3)